

# **Spectra Precision Survey Pro 4.8 GPS**

## **General Operations**

Topcon Receiver/Radio Configuration

One-Point Calibration

Multi-Point Calibration

Mapping Plane

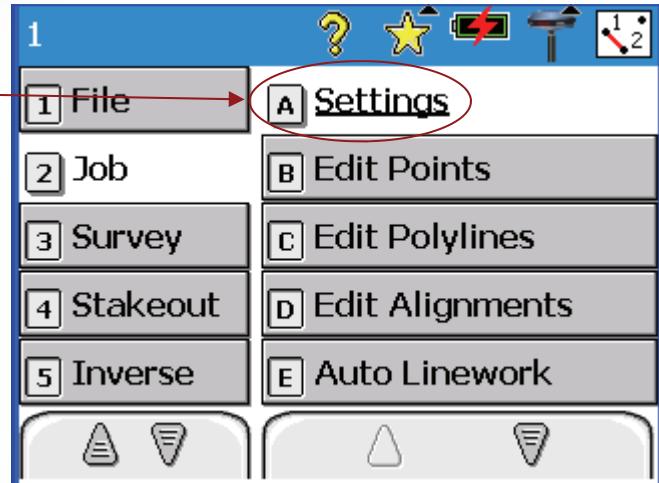
## **Procedures Manual**

# Creating a profile for the Topcon GPS Receiver

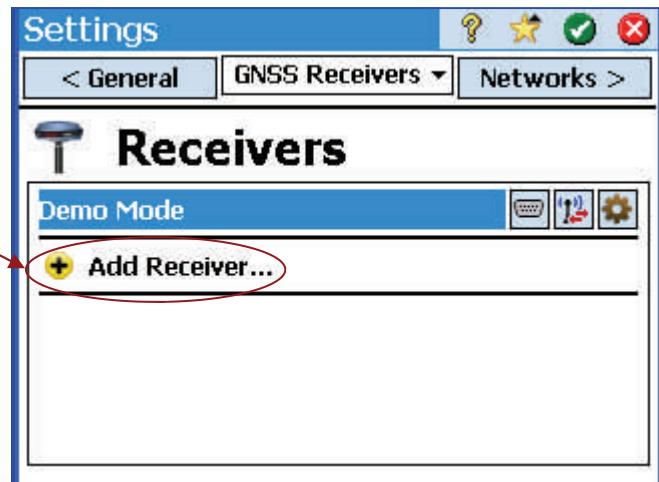


The following procedure will create a profile for your Topcon GPS receiver. This only needs to be done once per receiver. Make sure the receiver is ON and within 10 ft of the data collector.

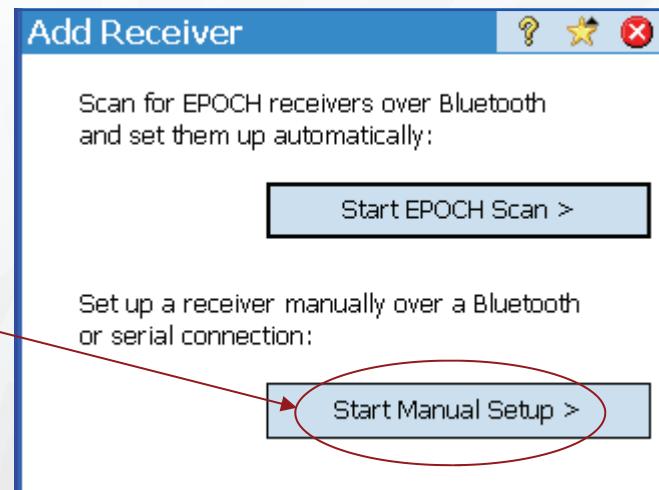
**Step 1:**  
Tap [Job] - [Settings]



**Step 2:**  
Tap [Add Receiver]



**Step 3:**  
Tap [Start Manual Setup]



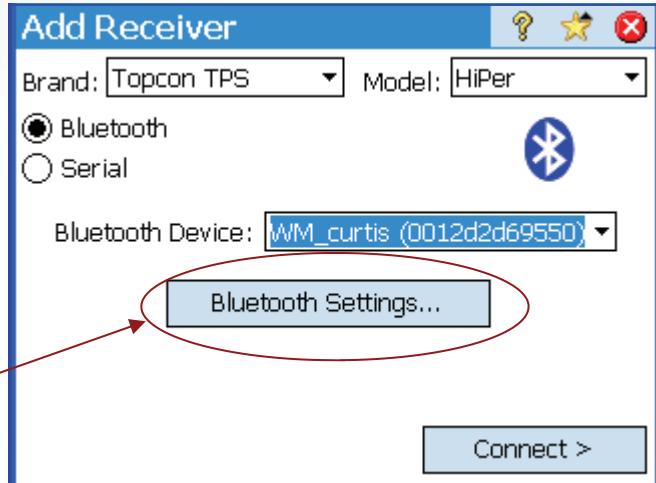
# Creating a profile for the Topcon GPS Receiver



## Step 4:

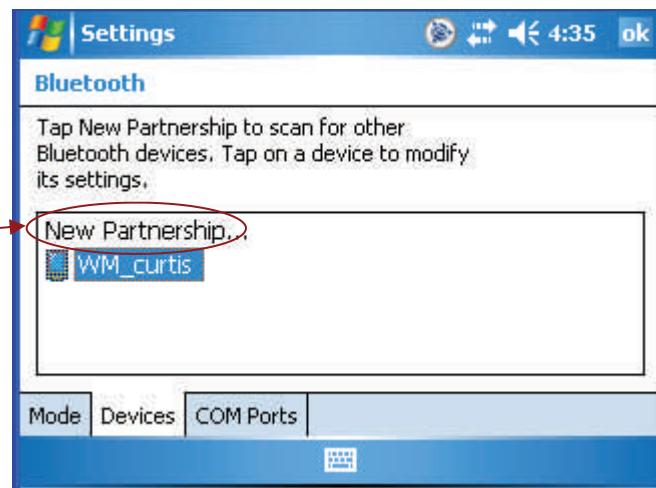
Set the dialog up as shown.

- Brand: Topcon TPS
- Model: (Select your GPS model)
- Bluetooth: (if using BT connection)



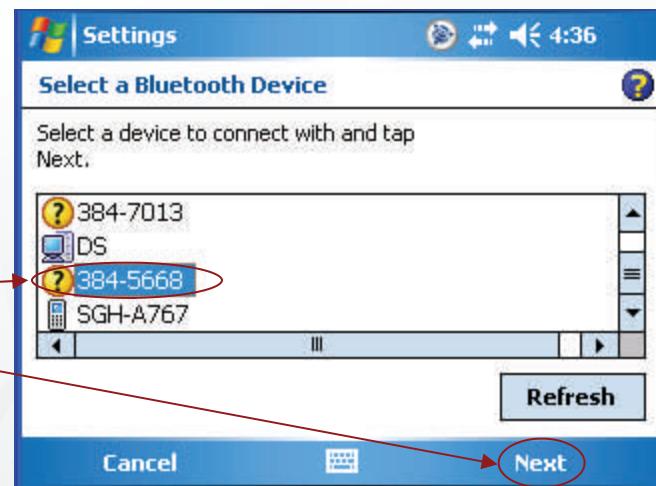
## Step 5:

If your Bluetooth connections have already been created **then** go to **Step 13 Else** tap [**Bluetooth Settings**] to create them.



## Step 6:

Tap [**New Partnership**]



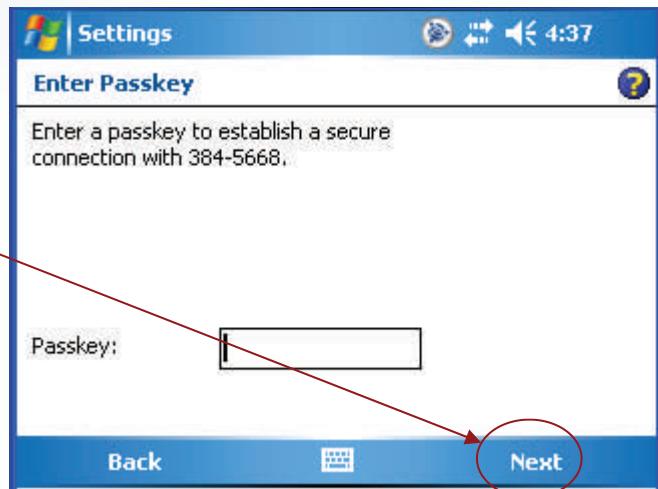
## Step 7:

Select your receiver off the list and press [**Next**]

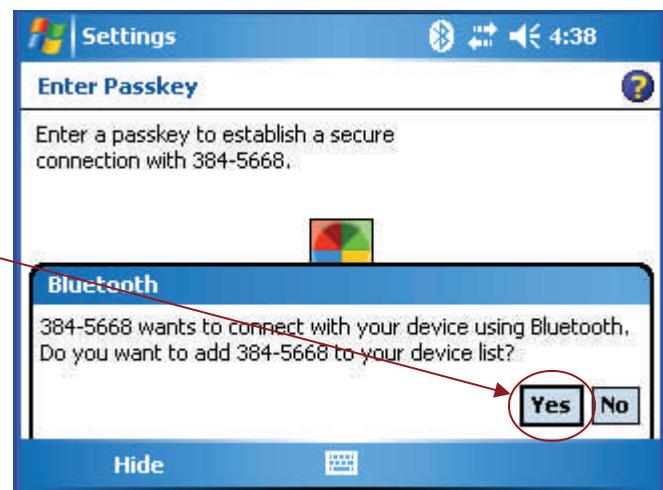
# Creating a profile for the Topcon GPS Receiver



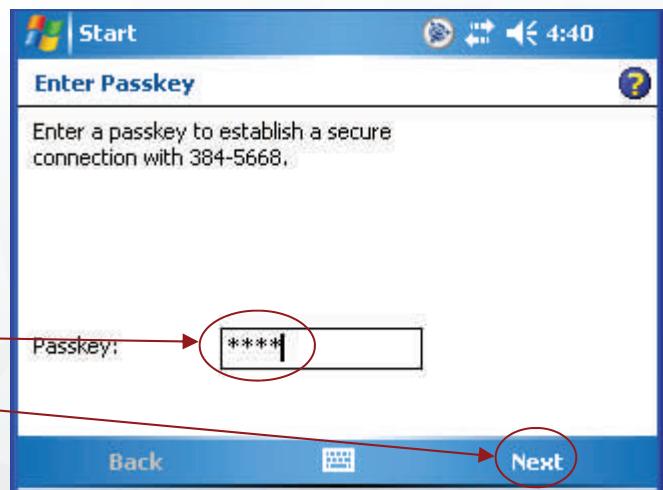
**Step 8:**  
Press [Next]



**Step 9:**  
Press [Yes]



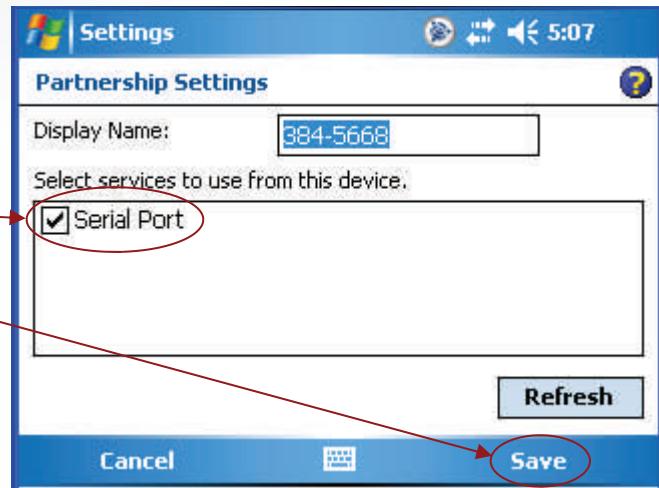
**Step 10:**  
Enter **1111** for the passkey  
and press [Next]



# Creating a profile for the Topcon GPS Receiver



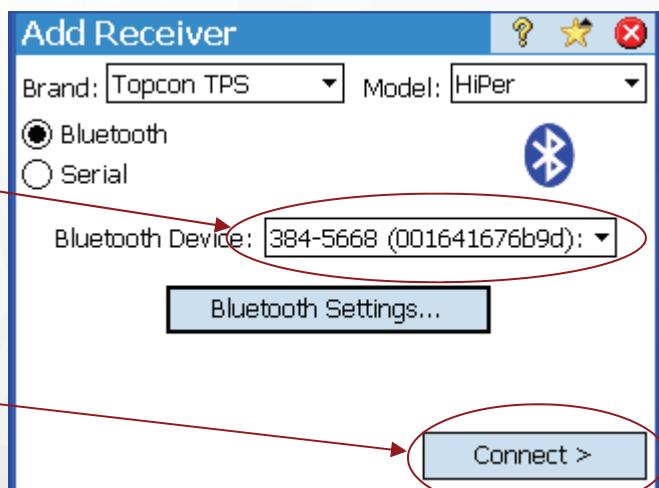
**Step 11:**  
Check [X] Serial Port and  
press [Save] or [Finish]



**Step 12:**  
Press [OK]



**Step 13:**  
Set the Bluetooth Device: to the blue-  
tooth connection we just created.



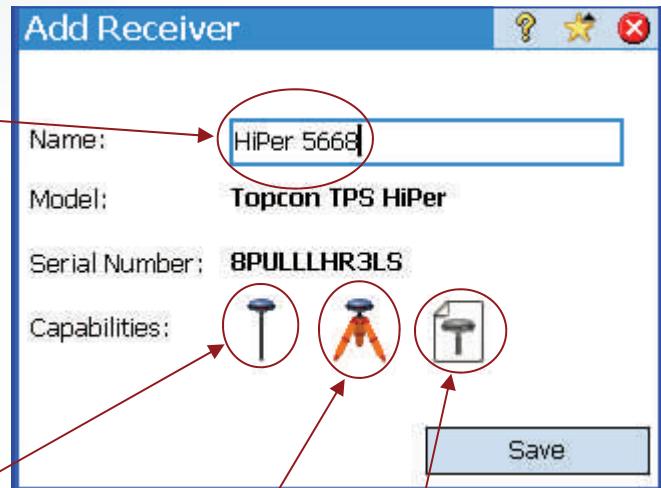
**Step 14:**  
Press [Connect]

# Creating a profile for the Topcon GPS Receiver



## Step 15:

Give the profile a specific name (Ie. serial number, HiPer 1, Dave, etc.) and press [Save]



### Note:

Spectra Precision does not recognize a receiver as a "Base" or "Rover". Any receiver with the capability to be a base or a rover can be used as either when selected.

### Note:

This symbol means the receiver can be used as a Rover.

### Note:

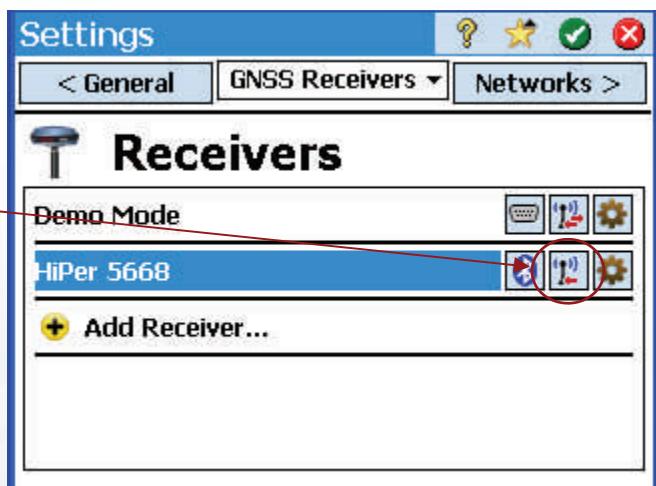
This symbol means the receiver can be used as a Base.

### Note:

This symbol means the receiver can be used for Post Processing.

## Step 16: Configure the Radio

Tap



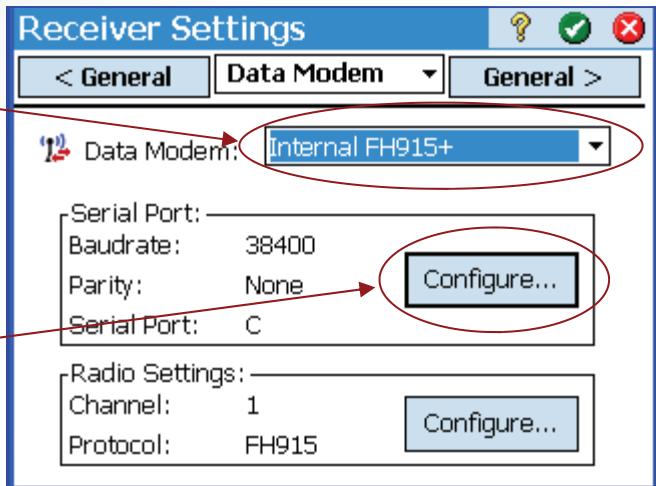
# Creating a profile for the Topcon GPS Receiver



## Step 17:

Set the Data Modem to the radio type of your GPS receiver.

- I.E. HiPer Lt is <**Internal FH915+**>
- HiPer GA is <**Internal D-UHF**>



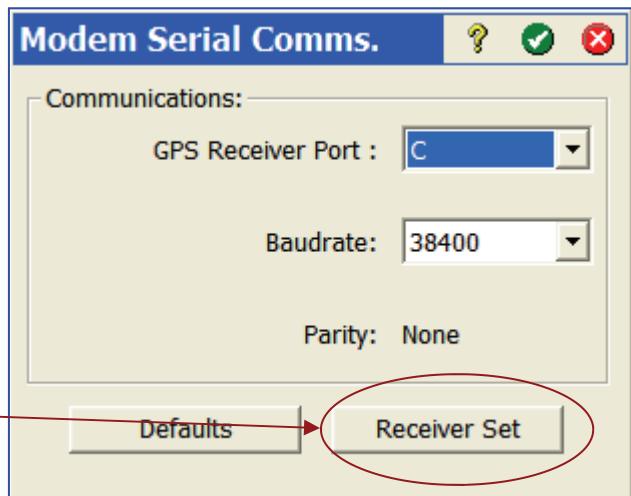
## Step 18:

Tap [Configure] to configure the serial port.

## Step 19:

- Set the Port to **C**
- Baudrate to **38400**.
- Parity to **None**

**Note:** Typical for HiPer Settings.

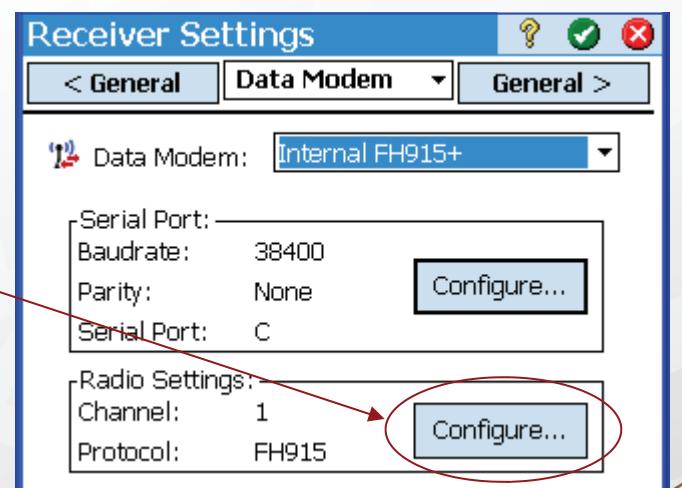


## Step 20:

Press [**Receiver Set**]

## Step 21:

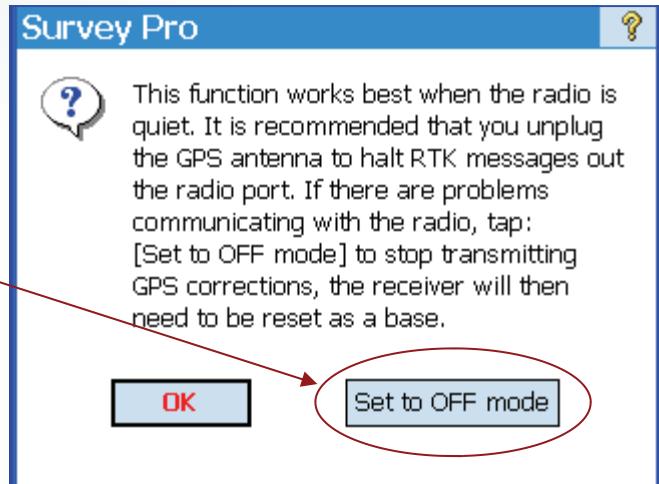
Press [**Configure**] to configure the Radio Settings.



# Creating a profile for the Topcon GPS Receiver

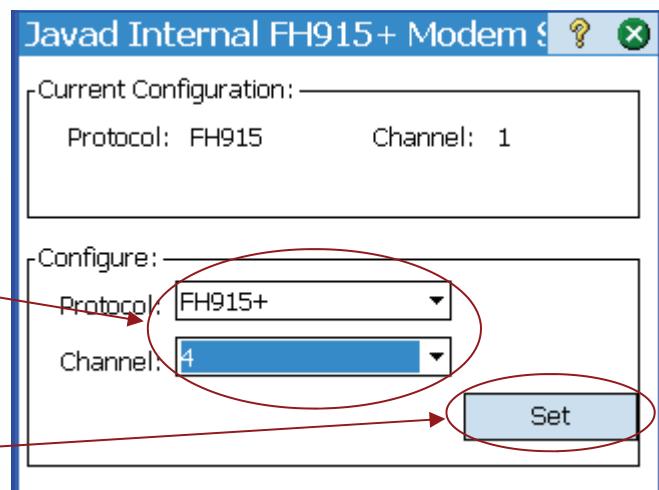


**Step 22:**  
Tap [Set to OFF mode]

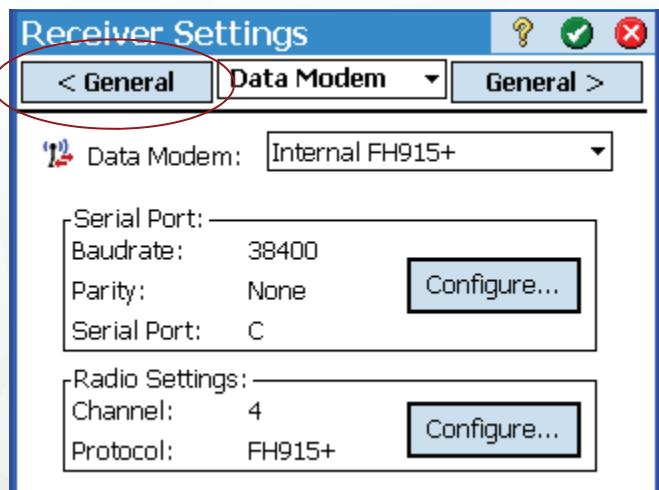


**Step 23:**  
Set the Protocol and Channel

**Step 24:**  
Tap [Set]



**Step 25:**  
Tap [General]



# Creating a profile for the Topcon GPS Receiver



## Step 26:

Set the user preferences in the <General tab>

- I.E. Elevation Cutoff to **10**
- Co Op Tracking to **ON**
- Multi Path Reduction to **ON**
- Confidence Level to **Medium**
- Antenna to **Internal** (Optional)

## Receiver Settings

< Data Modem | General | Data Modem >

Elevation Cutoff:	10
Co Op Tracking:	On
Multi Path Reduction:	On
Confidence Level:	Medium
Antenna:	internal

Set Rx. to OFF mode

## Step 27:

Tap

## Survey Pro



Your new setting will not take effect until you re-configure the base and/or rover.

OK

## Step 29:

Repeat **Step 2** to **Step 29** until all your receivers are entered.

## Step 30:

Tap To finish adding receivers.

## Settings

< General | GNSS Receivers | Networks >

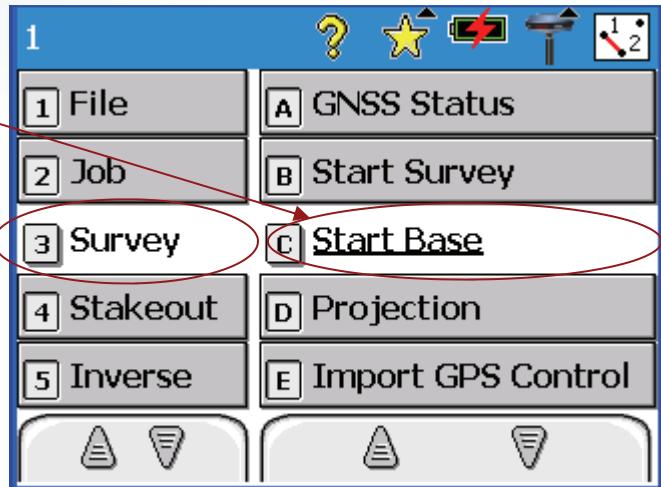
## Receivers

Demo Mode	
HiPer 5668	
+ Add Receiver...	

# One-Point Setup Base and Rover



**Step 1:**  
Tap [Survey] - [Start Base]



## Step 2:

- Select a receiver to be the Base (**Note:** this can be any receiver you have profiled.)
- Set the Correction Format (typically CMR+)
- Make sure your base is in proximity, powered on and ready to work.
- Press [Connect]

## Connect to Base

Select RTK Base:

HiPer 5668

HiPer 7013

Demo Mode

Internal FH915+

Correction Format: CMR +plus

Use CMP Station Index: 29

**Connect >**

## Step 3:

Since we are assuming a simple one point setup, Press [Ground Calibration]

## Easy Start Survey Prompt Project

Select a projection mode:

Use Ground Calibration: \_\_\_\_\_

Choose this mode if you are doing a ground level survey with no projection and no datum for GPS

**Ground Calibration >**

Use Mapping Plane: \_\_\_\_\_

Choose this mode if you will select a map projection from the coordinate system database.

**Mapping Plane >**

Don't ask me again.

# One-Point Setup Base and Rover



## Step 4:

If this is a new setup, we need to set the antenna profile. Press [Setup]

Start Survey Wizard

Auton. Radio: 0% SV: 07 HRMS: 8.22

Base Receiver

Base is ready to set.  
Check the antenna height then tap [Next >].

Base Antenna: \_\_\_\_\_

Type: Hiper

Measured: --- To: Slant measure mark

Post Processing Recording Interval: Off

**Setup ...**

**Next >**

## Step 5:

- Set the Antenna Type to the correct model. (HiPer for all HiPer Receivers)
- Set the Measure To: (Typically Slant on the Base)
- Enter in the measure-up value.
- Press [Set]

Base Receiver Antenna

Antenna Type: Hiper

Measure To: Slant measure mark

Measured: 6.0

Radius: 0.250 usft

Offset: 0.248 usft

Serial: \_\_\_\_\_

Notch: 1

**Set**

## Step 6: Tap [Next]

Start Survey Wizard

Auton. Radio: 0% SV: 08 HRMS: 7.84

Base Receiver

Base is ready to set.  
Check the antenna height then tap [Next >].

Base Antenna: \_\_\_\_\_

Type: Hiper

Measured: 6.000 usft To: Slant measure mark

Post Processing Recording Interval: Off

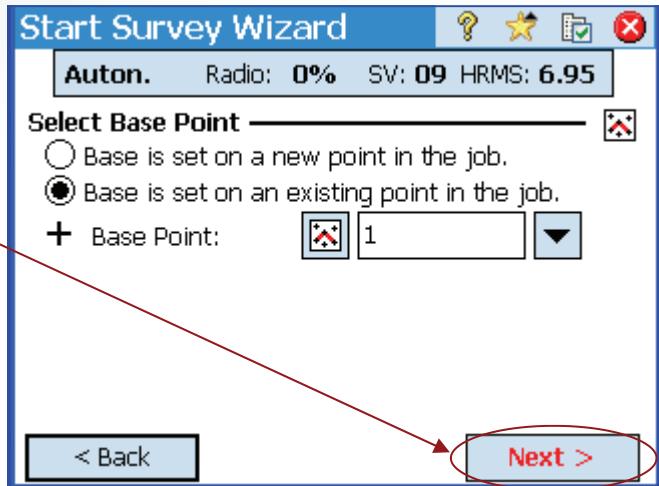
**Next >**

# One-Point Setup Base and Rover



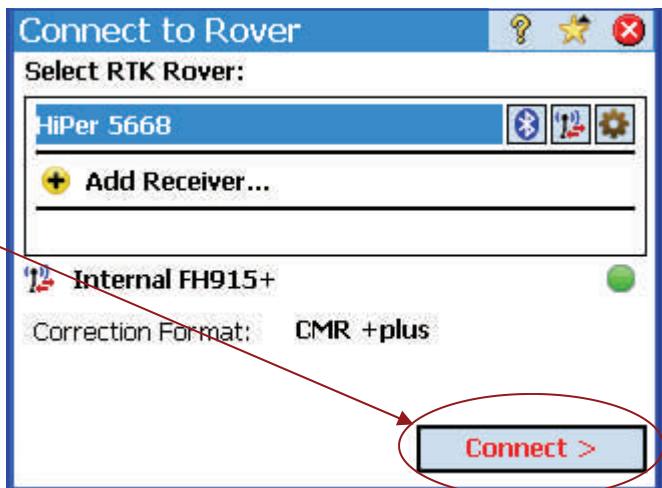
## Step 7:

- Make sure [x] Base is set on existing point.. is checked. (Default)
- Press [**Next**]



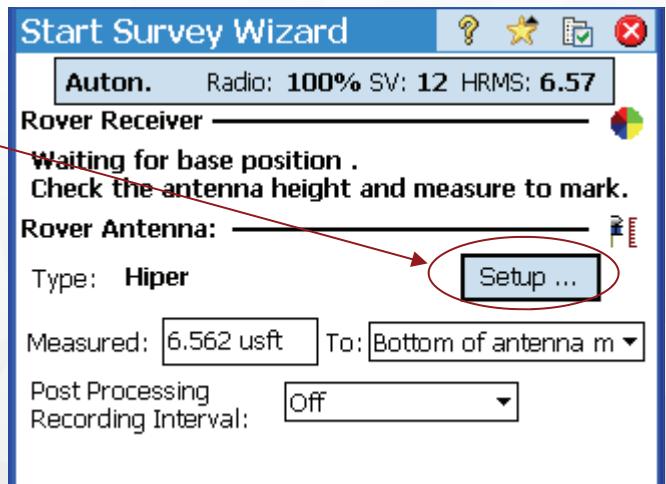
## Step 8:

- Select the receiver you want to use as a Rover.
- Press [**Connect**]



## Step 9:

If this is a new setup, we need to set the antenna profile. Press [**Setup**]



# One-Point Setup Base and Rover



## Step 10:

- Set the Antenna Type to the correct model. (HiPer for all HiPer Receivers)
- Set the Measure To: (Typically Bottom of Mount on the Rover)
- Enter in the measure-up value.
- Press [Set]

Rover Receiver Antenna

Antenna Type: Hiper

Measure To: Bottom of antenna mount

Measured: 6.562 usft

Offset: 0.348 usft

Serial: \_\_\_\_\_

**Set**

**Step 11:**  
Tap [Next]

Start Survey Wizard

Fix Radio: 100% SV: 07 HRMS: 0.06

Rover Receiver

Rover receiver is ready to set.  
Check the antenna height then tap [Next >].

Rover Antenna: \_\_\_\_\_

Type: Hiper

Measured: 6.562 usft To: Bottom of antenna m

Post Processing Recording Interval: Off

**Next >**

**Step 12:**  
For one-point Setup,  
press [One Point]

Start Survey Wizard

Fix Radio: 100% SV: 08 HRMS: 0.04

GPS Resection

You can enter points for GPS control.

Or:

Start with one point calibration scaled for ground distances at h = 667.695 usft.

**One Point**

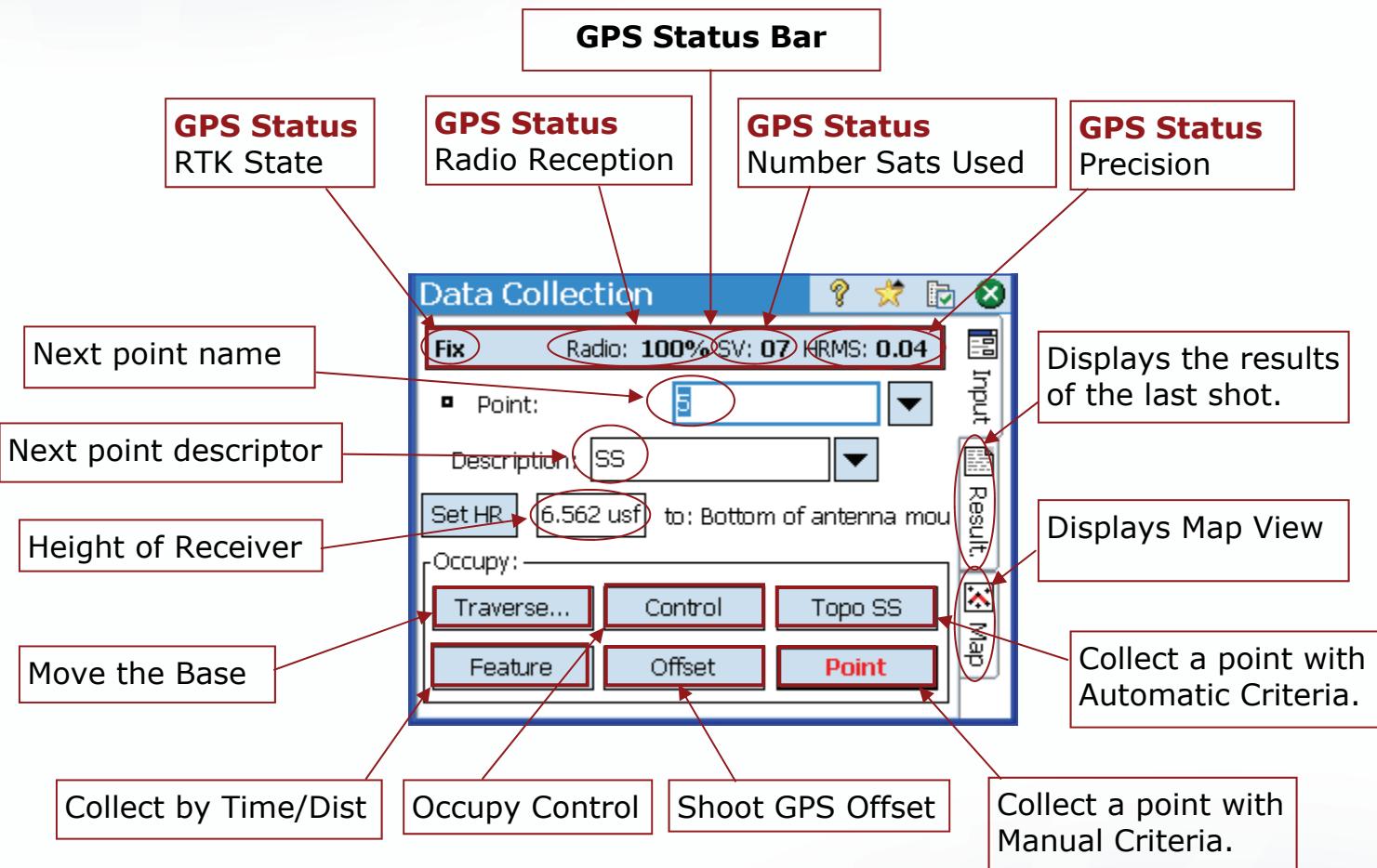
Start Surveying Now  
Solve one point calibration at base.

< Back

# One-Point Setup Base and Rover



## Anatomy of the Data Collection Dialog



### Step 13:

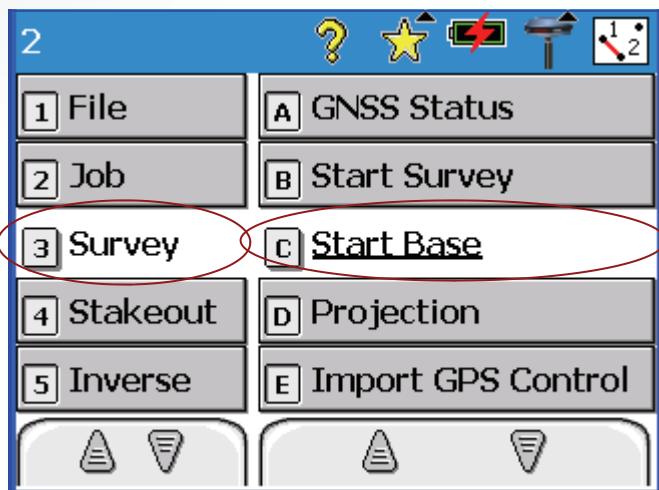
Survey Pro should go Fixed and you can begin work.

# Multi-Point Calibration (Localization)



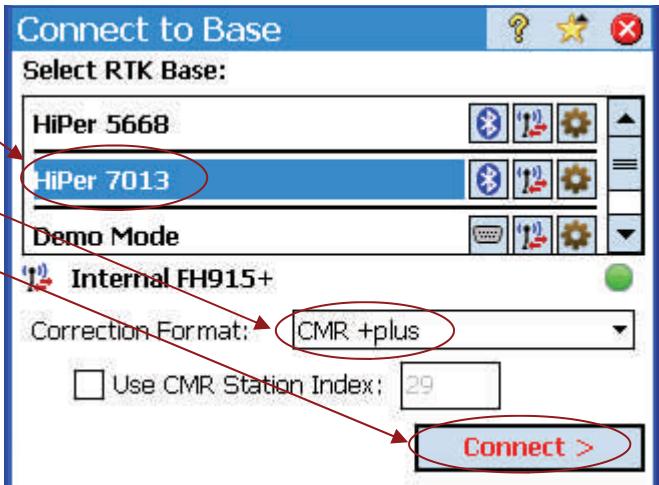
This procedure assumes you have a base and rover setup and that you are localizing (calibrating) into an existing ground system for the first time. For further reading on Calibration see "Introduction to RTK GPS" on [www.hayeshelp.com](http://www.hayeshelp.com).

**Step 1:**  
Tap [Survey] - [Start Base].

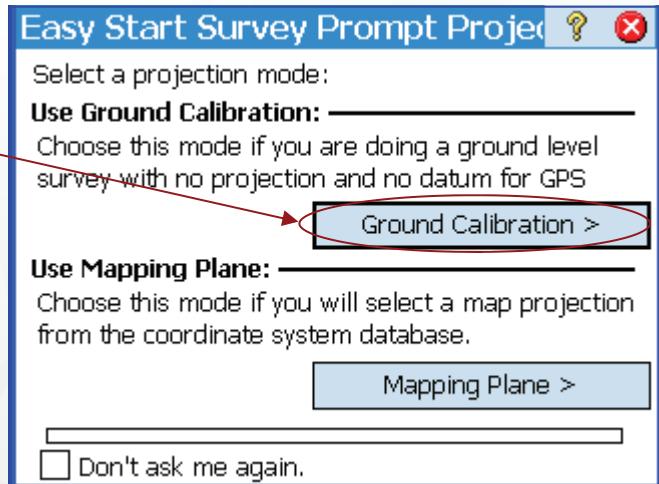


## Step 2:

- Select the receiver profile to use as a base.
- Set the Correction Format. (CMR+ or RTCM 3.0 are good)
- Press [Connect]



**Step 3:**  
Tap [Ground Calibration]

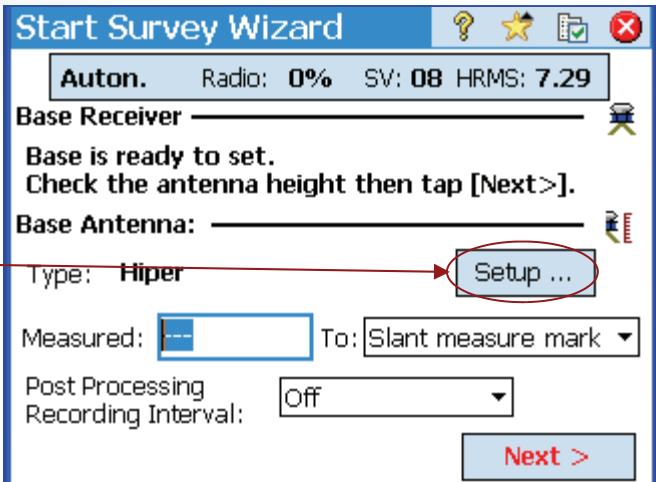


# Multi-Point Calibration (Localization)



## Step 4-

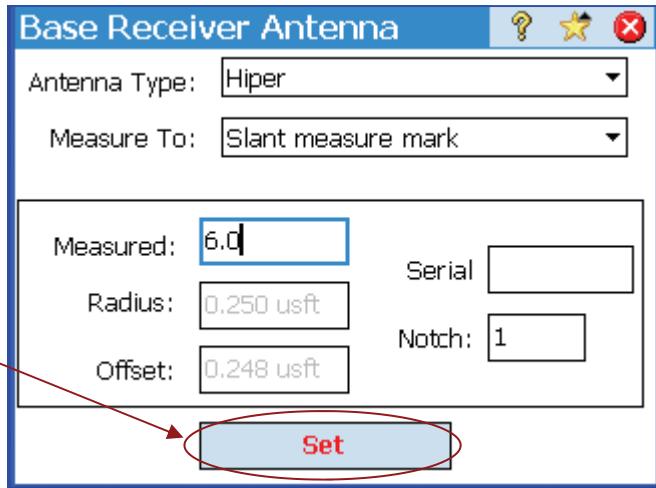
- **If**—The antenna is already configured—then enter the HR and skip to **step 6**
- **Else**—this is our first setup we will need to configure the GPS antenna for the first time. Press [**Setup**]



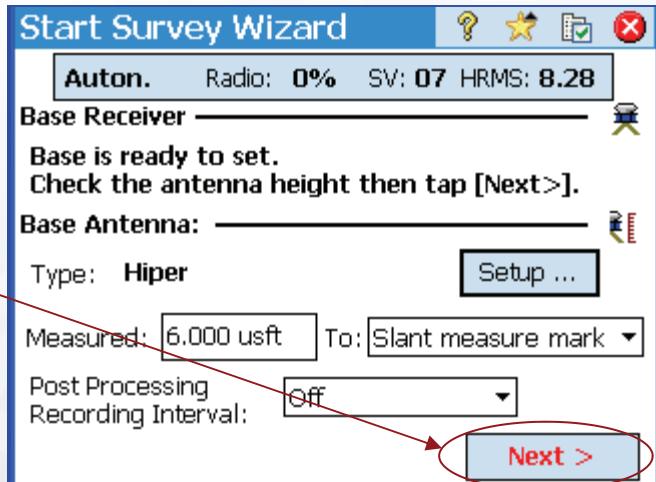
## Step 5:

Setup the Base Receiver Antenna.

- Set Antenna Type: (HiPer for all HiPer model receivers).
- Set the Measure to: (Typically slant for the base.—Nail to face of receiver).
- Enter the measured HR.
- Press [**Set**]



**Step 6:**  
Tap [**Next**]



# Multi-Point Calibration (Localization)

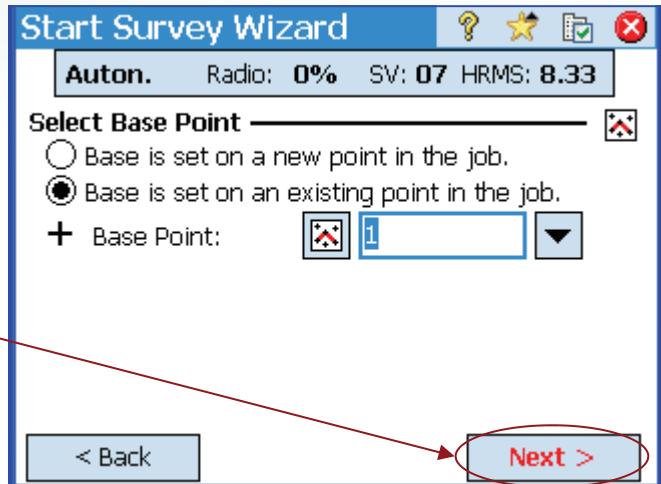


## Step 7:

Set the Base Point—

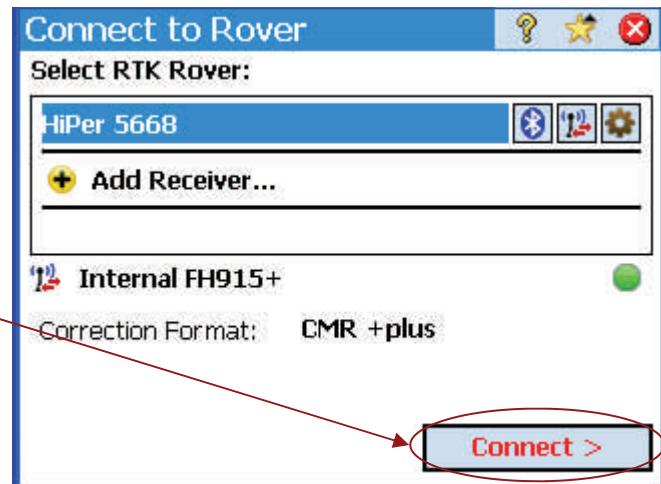
- Select whether the base is on a new point or an existing point.
- Enter the Base Point Name.
- Press [**Next**]

**Note\*** The base will automatically set.



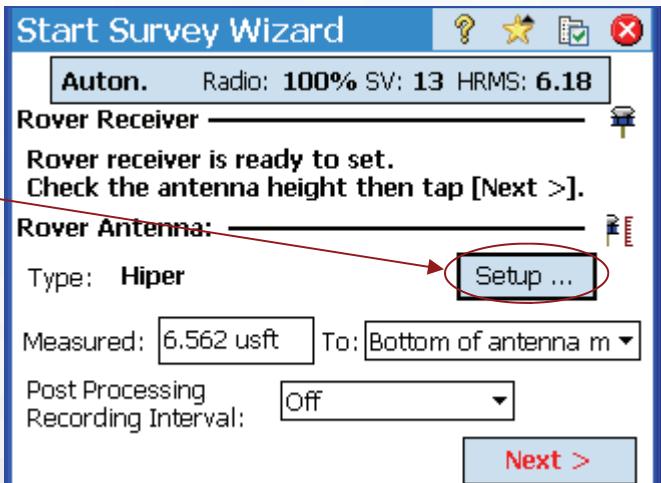
## Step 8:

- Select the receiver profile to use as a rover.
- Press [**Connect**]



## Step 9-

- **If**—The antenna is already configured—then enter the HR and skip to **Step 11**
- **Else**—this is our first setup we will need to configure the GPS antenna for the first time. Press [**Setup**]



# Multi-Point Calibration (Localization)



## Step 10:

Setup the Rover Receiver Antenna.

- Set Antenna Type: (HiPer for all HiPer model receivers).
- Set the Measure to: (Typically Bottom of Antenna mount for the Rover)
- Enter the measured HR.
- Press [Set]

Rover Receiver Antenna

Antenna Type: HiPer

Measure To: Bottom of antenna mount

Measured: 6.562 usft

Offset: 0.348 usft

Serial: \_\_\_\_\_

**Set**

## Step 11:

Tap [Next]

Start Survey Wizard

Fix Radio: 100% SV: 07 HRMS: 0.05

Rover Receiver

Rover receiver is ready to set.  
Check the antenna height then tap [Next >].

Rover Antenna:

Type: HiPer

Measured: 6.562 usft To: Bottom of antenna m

Post Processing Recording Interval: Off

**Next >**

## Step 12:

- If the base point elevation is used for a vertical benchmark then check the [x] Use Base as a Vertical Benchmark box.
- Press [Occupy Control] to occupy a calibration point.

Start Survey Wizard

Fix Radio: 100% SV: 07 HRMS: 0.04

GPS Backsight

Occupy a known point to create GPS control to orient the setup.

**Occupy Control >**

Base Point: 1

Use base as a vertical benchmark.

Start Surveying Now

Start now and occupy GPS control later.

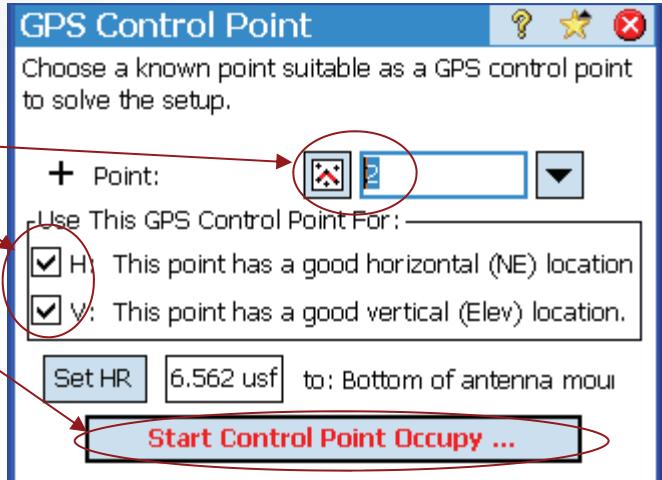
< Back

# Multi-Point Calibration (Localization)



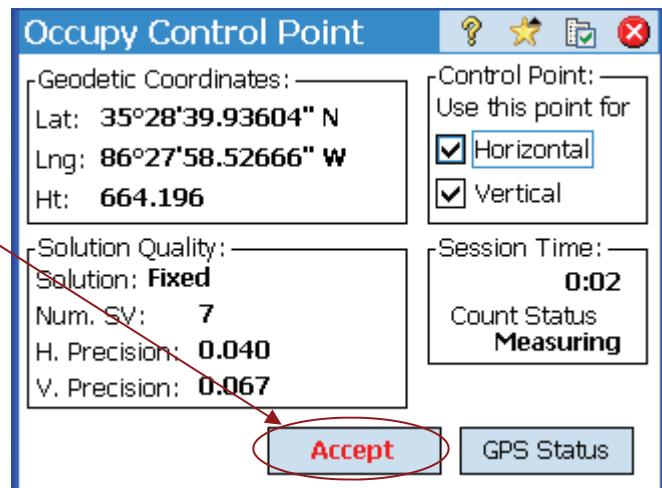
## Step 13:

- Choose the control point that you are occupying.
- Set whether holding the point for Horizontal, Vertical or both.
- Occupy the point very accurately and press [Start Control Point Occupy]



## Step 14:

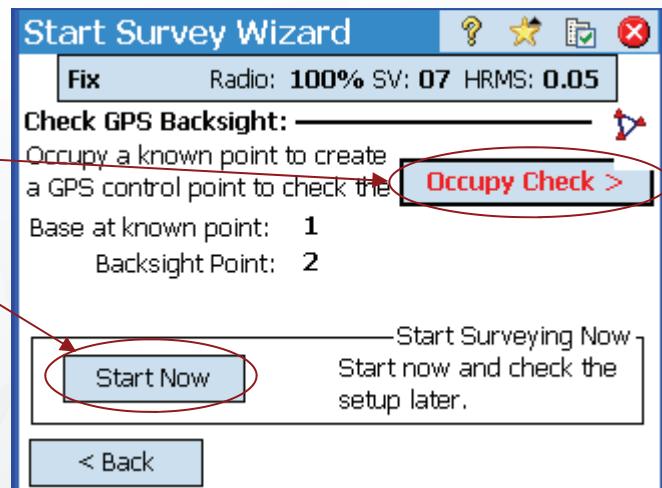
- Continue to occupy the point for at least 15 seconds.
- Press [Accept]



## Step 15:

**Note:** Spectra Precision now uses conventional survey terminology to describe the GPS occupation.

- Press [Start Now] to start a 2 point calibration solution. Go Survey you're done.
- Press [Occupy Check] to calibrate to an additional point.

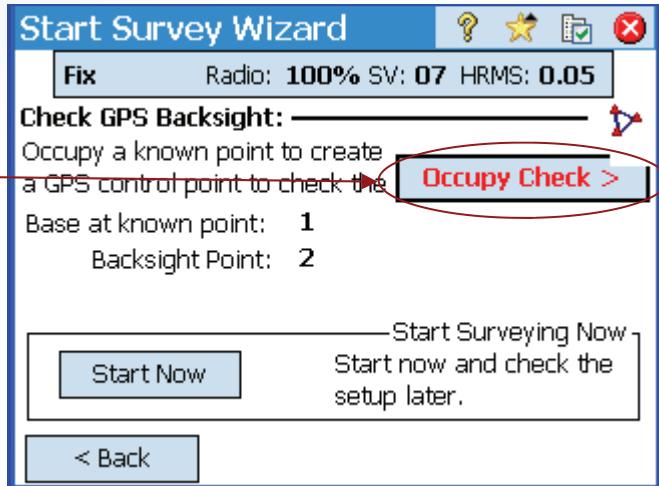


# Multi-Point Calibration (Localization)



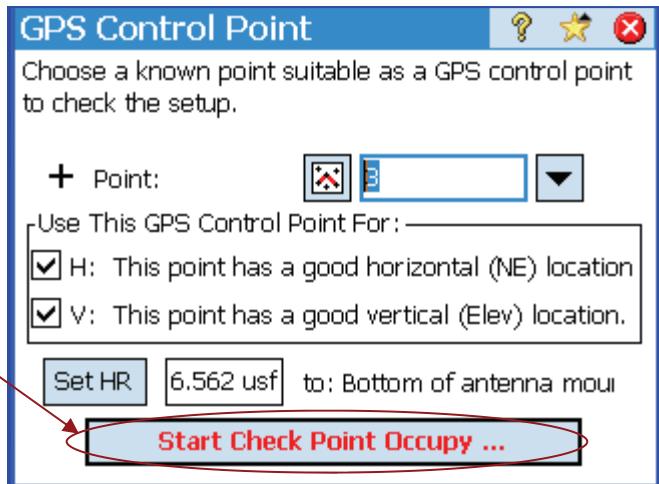
## Step 16:

- To add another control point, Press [Occupy Check]



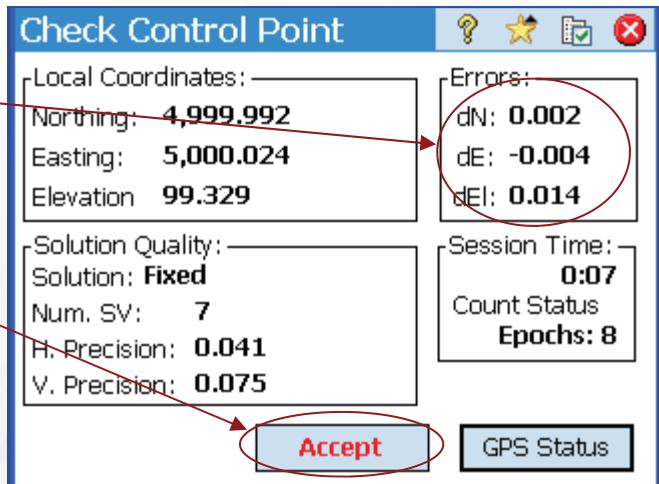
## Step 17:

- Choose the control point that you are occupying.
- Set whether holding the point for Horizontal, Vertical or both.
- Occupy the point very accurately and press [Start Control Point Occupy]



## Step 18:

- Note:** Survey Pro will display the difference between the calculated and measured position of the control point.
- Continue to occupy the point for at least 15 seconds.
- Press [Accept]



# Multi-Point Calibration (Localization)



## Anatomy of the Control Solution Dialog

The screenshot shows the 'Start Survey Wizard' dialog with the following interface elements:

- Fix:** A button at the top left.
- Radio: 100% SV: 07 HRMS: 0.05**: Status information at the top right.
- GPS Backsight:** A note below the status bar stating: "Control points are not spaced evenly, blunder detection cannot run. Tap [Finish] to apply anyway."
- Table:** A grid showing control points with columns: Name, H, V, N Err, E Err, V Err. Row 1 has circled '1' and 'Yes' under H and V. Row 2 has circled '2' and 'Yes' under H and V. Row 3 has circled '3' and 'Yes' under H and V. Row 1 also has circled values -0.002 and 0.009 under N Err and E Err respectively.
- Buttons:** "Add Point ...", "Show Details", "< Back", and "Finish".

**Note:** GPS Status Bar

**Note:** Used for Horizontal/Vertical Control

**Note:** North and East Error

**Note:** Control point #

**Note:** Add Point  
[Add Point] will take you back to Step 17.

**Note:** Projection Details

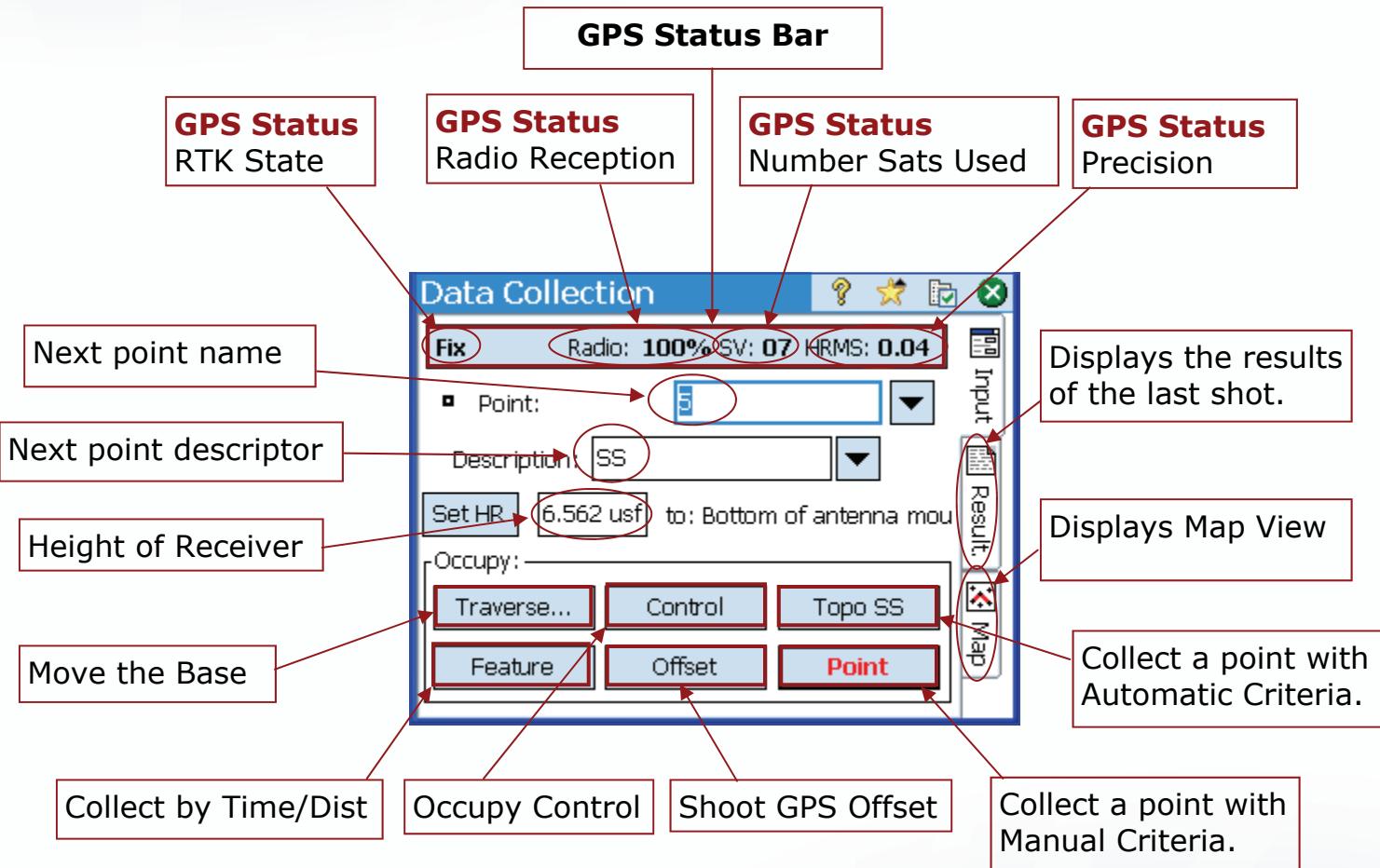
**Note:** Finish  
[Finish] will solve the projection and take you to Data Collection.

**Step 19:**  
**If**— You have more control points to add—Press [Add Point]  
**Else**—Press [Finish] to solve the projection and begin surveying.

# Multi-Point Calibration (Localization)



## Anatomy of the Data Collection Dialog

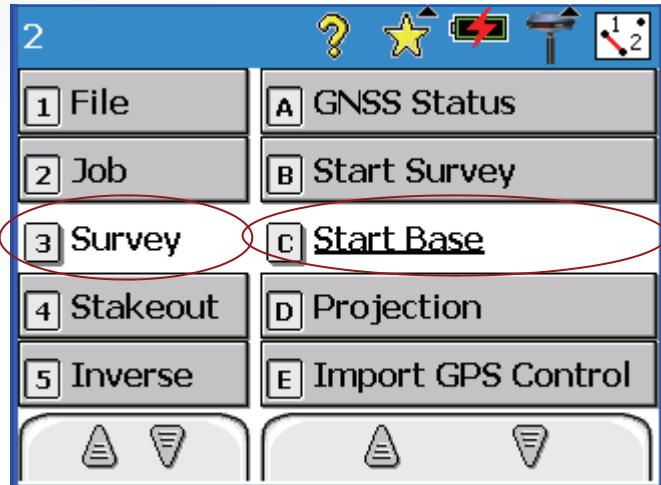


# Mapping Plane



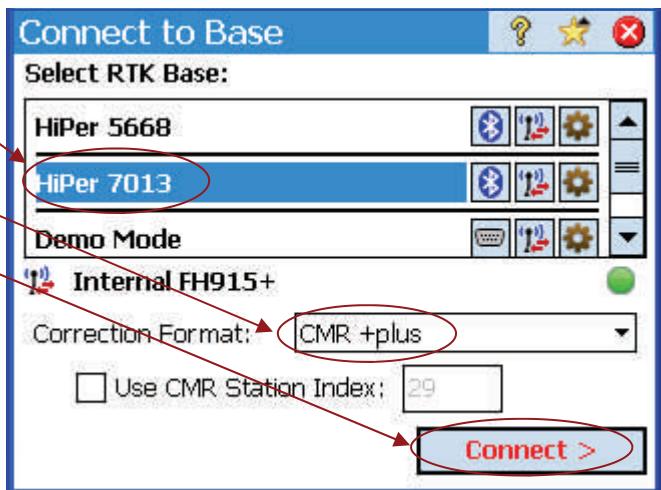
This procedure assumes you have a base and rover setup and that you are occupying into an existing mapping plane (I.e. NAD83 Tennessee 4100). For further reading on Mapping Plane see "Introduction to RTK GPS" on [www.hayeshelp.com](http://www.hayeshelp.com).

**Step 1:**  
Tap [Survey] - [Start Base].

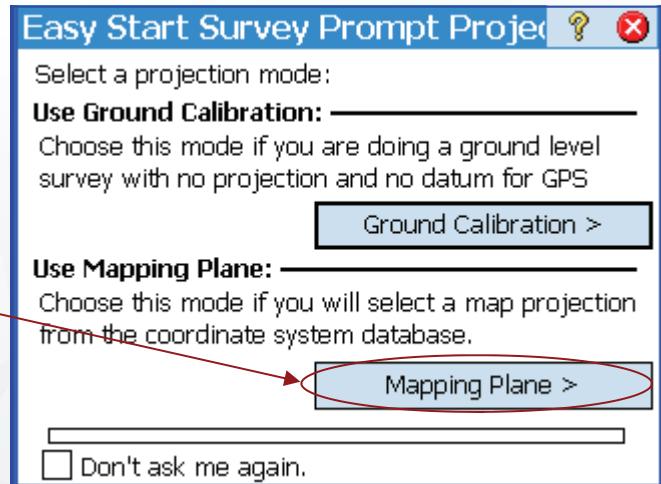


**Step 2:**

- Select the receiver profile to use as a base.
- Set the Correction Format. (CMR+ or RTCM 3.0 are good)
- Press [Connect]



**Step 3:**  
Tap [Mapping Plane]



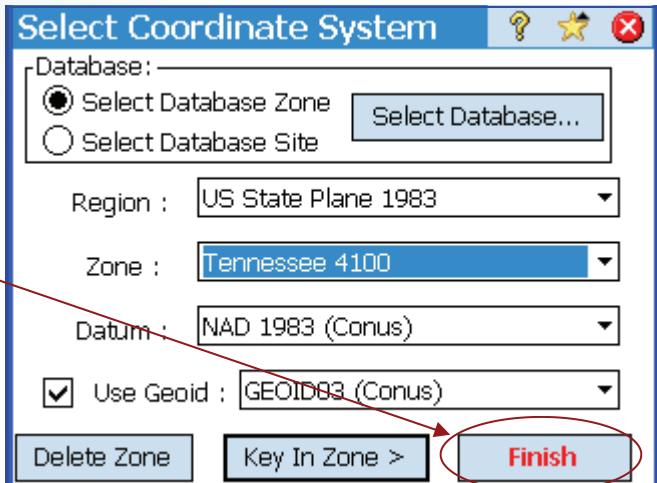
# Mapping Plane



## Step 4:

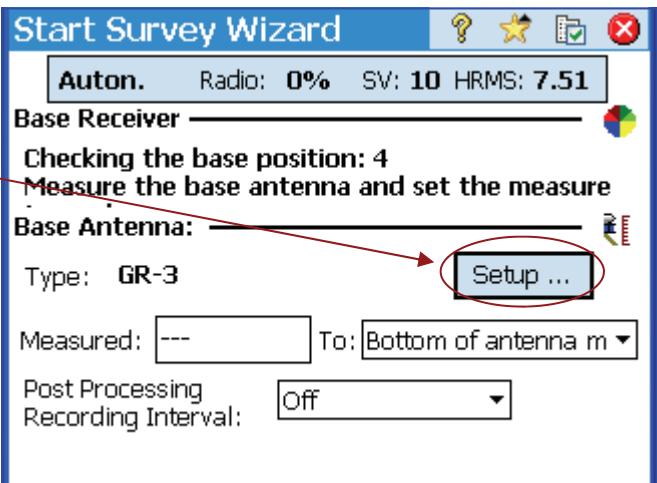
Set the Coordinate System.

- Check [x] Select Database Zone
- Set the Region (i.e US State Plane 1983)
- Set the Zone: (i.e. Tennessee 4100)
- Set the Datum: (NAD 1983)
- Check [x] Use Geoid: (Geoid03 files can be found on [www.hayeshelp.com](http://www.hayeshelp.com).)
- Press [**Finish**]



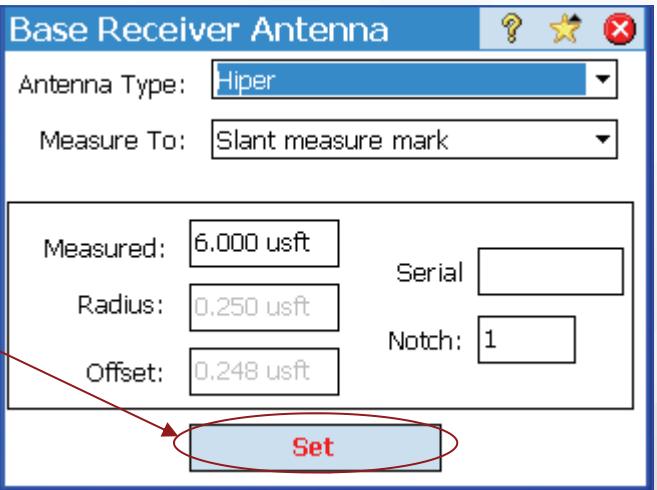
## Step 5-

- **If**— The antenna is already configured—then enter the HR and skip to **Step 7**
- **Else**—this is our first setup we will need to configure the GPS antenna for the first time. Press [**Setup**]



## Step 6:

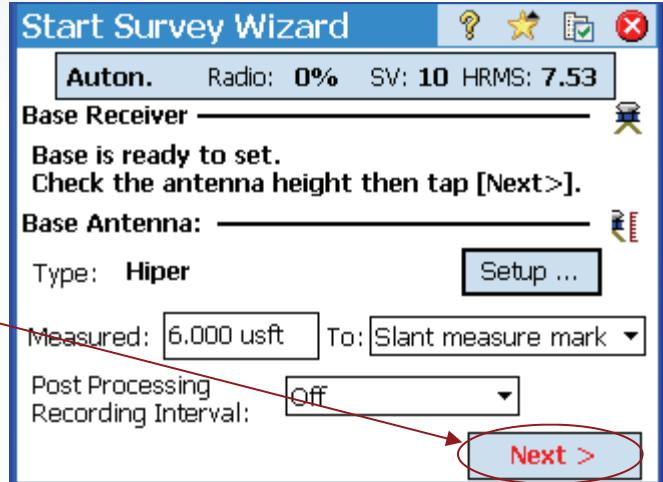
- Set the Antenna Type to the correct model. (HiPer for all HiPer Receivers)
- Set the Measure To: (Typically Slant on the Base)
- Enter in the measure-up value.
- Press [**Set**]



# Mapping Plane



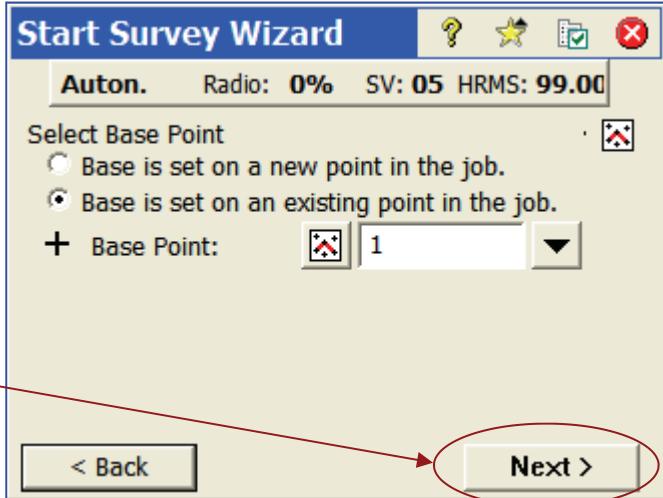
**Step 7:**  
Tap [Next]



## Step 8:

Set the Base Point—

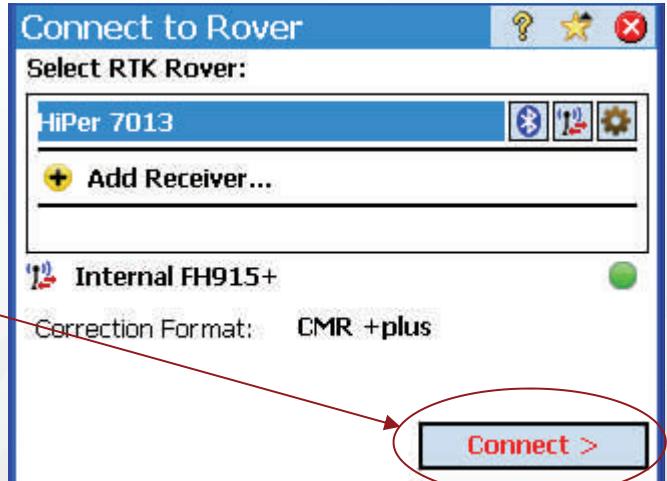
- **If**— Your Base is on a new point check  Base is set on a new point... Press [Next]
- **If** — your Base is on an existing point check  Base is set on an existing point.. Press [Next]
- **Note:** This document will use existing point operation.



## Step 9:

Connect to the Rover.

- Select the Receiver to be used as a Rover.
- Press [Connect]



# Mapping Plane



## Step 10-

- **If**— The antenna is already configured—then enter the HR and skip to **Step 12**
- **Else**—this is our first setup we will need to configure the GPS antenna for the first time. Press [**Setup**]

## Start Survey Wizard

Auton. Radio: 100% SV: 05 HRMS: 99.00

Rover Receiver

Rover receiver is ready to set.  
Check the antenna height then tap [Finish].

Rover Antenna: \_\_\_\_\_

Type: Manual Setup ...

Measured: 6.000 usft To: Slant measure

Post Processing Recording Interval: Off

Finish

## Step 11:

Setup the Rover Receiver Antenna.

- Set Antenna Type: (HiPer for all HiPer model receivers).
- Set the Measure to: (Typically Bottom of Antenna mount for the Rover)
- Enter the measured HR.
- Press [**Set**]

## Rover Receiver Antenna

Antenna Type: HiPer

Measure To: Bottom of antenna mount

Measured: 6.562 usft Serial: \_\_\_\_\_

Offset: 0.348 usft

Set

**Step 12:**  
Tap [**Finish**]

## Start Survey Wizard

Auton. Radio: 100% SV: 05 HRMS: 99.00

Rover Receiver

Rover receiver is ready to set.  
Check the antenna height then tap [Finish].

Rover Antenna: \_\_\_\_\_

Type: Manual Setup ...

Measured: 6.000 usft To: Slant measure

Post Processing Recording Interval: Off

Finish

# Mapping Plane



## Anatomy of the Data Collection Dialog

